

# RBR SENSORS



*RBRcoda*  
*RBRcoda<sup>3</sup>*

# INSTRUMENT GUIDE

[rbr-global.com](http://rbr-global.com)

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# 1 RBR sensors

The RBRcoda and RBRcoda<sup>3</sup> small smart sensors, as well as multi-channel sensors [RBRtridente](#) and [RBRquadrante](#), are a family of cabled instruments with high accuracy, low power consumption, and ability to endure harsh conditions. These realtime streaming sensors are easy to integrate into any RBR multi-parameter instrument, or connect directly via RS-232. Attach an MCIL connector with serial and power lines, and the data will stream.

The RBR sensors are a perfect choice for many oceanographic and limnology applications where realtime streaming of data is desired, such as borehole monitoring, remotely operated underwater vehicles, stream gauging, or harbour water levels. These completely sealed units are available in plastic or titanium housings to accommodate shallow or deep deployments. Select from several | fast sampling variants, such as | fast8, | fast16, | fast32, and | tide16, depending on your needs.

**i** The RBRcoda<sup>3</sup> D | tide16 and RBRcoda<sup>3</sup> T.D | tide16 take averages of pressure readings over extended periods of time, providing accurate tide level data.

**i** The RBRquadrante, RBRtridente, and RBRcoda Tu support aggregate sampling mode, where measurement bursts are taken at a selected period.

## Shallow variants

- RBRcoda<sup>3</sup> D - pressure (depth)
- RBRcoda<sup>3</sup> T - temperature
- RBRcoda<sup>3</sup> T.D - temperature, pressure
- RBRcoda<sup>3</sup> DO (OxyGuard®) - dissolved oxygen
- RBRcoda<sup>3</sup> PAR - photosynthetically active radiation
- RBRcoda<sup>3</sup> rad - narrow-band light radiation
- RBRcoda<sup>3</sup> PAR (LI-COR®) - photosynthetically active radiation

## Deep variants

- RBRcoda<sup>3</sup> D | deep - pressure (depth)
- RBRcoda<sup>3</sup> T | deep - temperature
- RBRcoda<sup>3</sup> T.D | deep - temperature, pressure
- RBRcoda<sup>3</sup> T.ODO - temperature, optical dissolved oxygen
- RBRcoda<sup>3</sup> PAR | deep - photosynthetically active radiation
- RBRcoda<sup>3</sup> rad | deep - narrow-band light radiation
- RBRcoda Tu - turbidity



**i** The RBRcoda<sup>3</sup> T.ODO and RBRcoda Tu are only available as a deep variant in titanium housing.

**i** For multi-channel sensor variants, see the dedicated [RBRtridente](#) and [RBRquadrante Instrument Guide](#).

## 2 Specifications

The RBR smart realtime sensors have highly competitive specifications. They are designed for streaming data via RS-232 cable and thus have no onboard memory. Most have only one channel, but some include two, three, or four. Refer to the individual pages for the RBRcoda<sup>3</sup> D, RBRcoda<sup>3</sup> T, RBRcoda<sup>3</sup> T.D, RBRcoda<sup>3</sup> T.ODO, RBRcoda<sup>3</sup> PAR / RBRcoda<sup>3</sup> rad, and RBRcoda Tu, as well as our instruments with third-party sensors, the RBRcoda<sup>3</sup> DO (OxyGuard) and the RBRcoda<sup>3</sup> PAR (LI-COR®).

Please contact the [RBR sales team](#) to discuss your needs and to select the perfect configuration for your applications.

### 2.1 RBRcoda<sup>3</sup> D

The RBRcoda<sup>3</sup> D and RBRcoda<sup>3</sup> D | deep use the piezoresistive pressure sensors.

The sensor is protected by a clear plastic guard. During deployments, always orient the sensor downwards to reduce debris collecting in the housing.



**RBRcoda<sup>3</sup> D and RBRcoda<sup>3</sup> D | deep**

#### Pressure

Parameter	Value
Range	20 / 50 / 100 / 200 / 500 / 1000dbar (plastic) 1000 / 2000 / 4000 / 6000dbar (Ti)
Initial accuracy	±0.05% full scale
Resolution	<0.001% full scale
Typical stability	±0.05% full scale / year
Time constant	<10ms

## Physical

Parameter	Value
Housing	Plastic or titanium
Diameter	25mm
Length	~200mm (~235mm with connector)
Weight	170g in air, 70g in water (plastic) 370g in air, 270g in water (Ti)
Depth rating	Up to 1000m (plastic) Up to 6000m (Ti)
Sampling rate	2Hz standard 8Hz   fast8 16Hz   fast16,   tide16 32Hz   fast32

## Power

Parameter	Value
Supply voltage	6V to 18V (12V nominal)
Power	10mA/120mW at 12V

## 2.2 RBRcoda<sup>3</sup> T

The RBRcoda<sup>3</sup> T and RBRcoda<sup>3</sup> T | deep use the same thermistor-type temperature sensor. The thermistor on the RBRcoda<sup>3</sup> T | slow | deep is embedded, making the sensor extremely robust and deployable in the most challenging environments, such as boreholes and industrial settings.



**RBRcoda<sup>3</sup> T, RBRcoda<sup>3</sup> T | deep, and RBRcoda<sup>3</sup> T | slow | deep**

## Temperature

Parameter	Value
Range*	-5°C to 35°C
Initial accuracy	±0.002°C
Resolution	<0.00005°C
Typical stability	±0.002°C / year
Time constant	<0.1s   fast, <1s standard, <15s   slow

\*A wider temperature range is available upon request. Contact [RBR](#) for more information.

## Physical

Parameter	Value
Housing	Plastic or titanium
Diameter	25mm
Length	~210mm (~245mm with connector) ~195mm (~230mm with connector)   slow   deep
Weight	160g in air, 60g in water (plastic) 390g in air, 280g in water (Ti)
Depth rating	Up to 1700m (plastic) Up to 6000m (Ti)
Sampling rate	1Hz   slow 2Hz standard 8Hz   fast8 16Hz   fast16 32Hz   fast32

## Power

Parameter	Value
Supply voltage	6V to 18V (12V nominal)
Power	10mA/120mW at 12V

## 2.3 RBRcoda<sup>3</sup> T.D

The RBRcoda<sup>3</sup> T.D and RBRcoda<sup>3</sup> T.D | deep use the thermistor-type temperature sensors and piezoresistive pressure sensors. The pressure sensor is protected by a clear plastic guard.



**RBRcoda<sup>3</sup> T.D and RBRcoda<sup>3</sup> T.D | deep**

### Temperature

Parameter	Value
Range*	-5°C to 35°C
Initial accuracy	±0.002°C
Resolution	<0.00005°C
Typical stability	±0.002°C / year
Time constant	<0.1s   fast, <1s standard

\*A wider temperature range is available upon request. Contact [RBR](#) for more information.

### Pressure

Parameter	Value
Range	20 / 50 / 100 / 200 / 500 / 1000dbar (plastic) 1000 / 2000 / 4000 / 6000dbar (Ti)
Initial accuracy	±0.05% full scale
Resolution	<0.001% full scale
Typical stability	±0.05% full scale / year
Time constant	<10ms

## Physical

Parameter	Value
Housing	Plastic or titanium
Diameter	25mm
Length	~265mm (~300mm with connector)
Weight	190g in air, 70g in water (plastic) 390g in air, 280g in water (Ti)
Sampling rate	2Hz standard 8Hz   fast8 16Hz   fast16,   tide16 32Hz   fast32



The depth rating of the RBR*coda*<sup>3</sup> T.D and RBR*coda*<sup>3</sup> T.D | deep instruments is determined by the depth rating of the pressure sensor installed.

For example, the RBR*coda*<sup>3</sup> T.D in plastic housing with a 200dbar pressure sensor cannot be used at depths greater than 200m, even though the temperature sensor is rated at 1700m.

## Power

Parameter	Value
Supply voltage	6V to 18V (12V nominal)
Power	10mA/120mW at 12V

## 2.4 RBR*coda*<sup>3</sup> T.ODO

The RBR*coda*<sup>3</sup> T.ODO uses the optical dissolved oxygen sensor, with three time constant options available: 1s, 8s, and 30s. The | fast (1s time constant) variant is well suited for profiling applications. The | slow (30s time constant) version has a protective layer to facilitate automated cleaning by a wiper to keep it free from biofouling during long-term moored deployments.

During deployments, always orient the sensor downwards to reduce debris collecting at the aperture and minimise direct sunlight. Store the sensor in the dedicated storage cap, included with the instrument. Rehydrate for five days before deployment. See [RBR ODO sensor care and maintenance](#) for more information.



**RBRcoda<sup>3</sup> T.ODO | fast and RBRcoda<sup>3</sup> T.ODO | slow**

### Dissolved oxygen

Parameter	Value
Measurement range	0-1000µmol/L
Calibrated range	
Concentration	0-500µmol/L
Saturation	0-120%
Temperature	1.5°C to 30°C
Initial accuracy	
For   fast	Maximum of ±8µmol/L or ±5%
For standard,   slow	Maximum of ±2µmol/L or ±1.5%
Resolution	
For   fast	<1µmol/L (saturation 0.4%)
For standard	<0.5µmol/L (saturation 0.2%)
For   slow	<0.1µmol/L (saturation 0.04%)
Time constant	<1s   fast, <8s standard, or <30s   slow

**⚠** Optical dissolved oxygen measurements require pressure correction for highest accuracy. When installed on an instrument with a pressure sensor, this correction is done automatically. If deployed as a standalone sensor or installed on a moored instrument with no pressure sensor, enter the known absolute pressure value manually in the table under the **Parameters** tab in Ruskin.

## Temperature

Parameter	Value
Range*	-5°C to 35°C
Initial accuracy	±0.002°C
Resolution	<0.00005°C
Typical stability	±0.002°C / year
Time constant	<1s

\*A wider temperature range is available upon request. Contact [RBR](#) for more information.

## Physical

Parameter	Value
Housing	Titanium
Diameter	28mm
Length	~125mm, ~160mm (with connector)
Weight	180g in air, 110g in water
Depth rating	Up to 6000m
Sampling rate	24hr to 1Hz

## Power

Parameter	Value
Supply voltage	7V to 15V (12V nominal)
Power	10mA for 300ms (36mJ/sample)   fast 10mA for 300ms (36mJ/sample) standard 10mA for 500ms (60mJ/sample)   slow
Sleep current	60µA

## Output values

- Temperature (°C)
- Dissolved O<sub>2</sub> concentration (µmol/L)
- Dissolved O<sub>2</sub> concentration (salinity compensated, µmol/L)
- Dissolved O<sub>2</sub> saturation (%)
- Dissolved O<sub>2</sub> phase (°)

## 2.5 RBRcoda<sup>3</sup> PAR, RBRcoda<sup>3</sup> rad

The RBRcoda<sup>3</sup> PAR and RBRcoda<sup>3</sup> rad instruments look identical and share several specifications.

The RBRcoda<sup>3</sup> PAR and RBRcoda<sup>3</sup> PAR | deep use the cosine photosynthetically active radiation sensors which can measure light within one hemisphere.

The RBRcoda<sup>3</sup> rad and RBRcoda<sup>3</sup> rad | deep use radiometers measuring narrow-band light with a fixed channel width, available in various 10nm- and 25nm-wide channels. Both centre wavelength and channel width are factory-configured.



**RBRcoda<sup>3</sup> PAR and RBRcoda<sup>3</sup> PAR | deep**

### Optical radiometry

Parameter	Value
Dynamic range	>5.5 decades (nominal)
Initial accuracy*	±2%
Linearity	±1%
Operating temperature range	-5°C to 35°C
Cosine response error (water)	±5% at 0-60°C, ±10% at 61-82°C
Azimuth error (water)	±1.5% at 45°C
Out-of-band rejection**	>25dB (typical), OD 2.5

\* RBR calibrates radiometers with NIST traceable references.

\*\* Out-of-band rejection is wavelength-dependent for narrow-band radiometers.

### PAR

Parameter	Value
Wavelength range	400nm to 700nm
Full scale range	0 to 5000µmol/m <sup>2</sup> /s (minimum)
Resolution	±0.010µ mol/m <sup>2</sup> /s

### Narrow-band channels

Parameter	Value
Centre wavelengths (CWL)*	413 / 445 / 475 / 488 / 508 / 532 / 560nm
Full width at half-maximum (FWHM)	10nm (25nm for CWL 475nm)
Full scale range	0 to 400 $\mu$ W/cm <sup>2</sup> /nm (minimum)
Resolution**	$\pm$ 0.001 $\mu$ W/cm <sup>2</sup> /nm

\* Other CWL options within the 400-1100nm range are available upon request. Contact [RBR](#) for more information.

\*\* Resolution is wavelength-dependent for narrow-band radiometers.

 Dark offset is internally temperature-compensated.

### Physical

Parameter	Value
Housing	Plastic or titanium
Diameter	25mm
Length	~235mm (~270mm with connector)
Weight	170g in air, 40g in water (plastic) 330g in air, 200g in water (Ti)
Depth rating	Up to 1000m (plastic) Up to 2000m (Ti)
Sampling rate	Up to 16Hz

### Power

Parameter	Value
Supply voltage	6-18V (12V nominal)
Power	77mJ per sample (1Hz or slower) 15mA/180mW (2Hz or faster)

## 2.6 RBRcoda Tu

The RBRcoda Tu is a realtime turbidity sensor with two independent optical channels for optimising linearity and sensitivity. Its high dynamic range permits exposure to full sunlight with very low detection limits, while power consumption and depth rating have been tailored for use in a wide variety of applications.

The turbidity channel of the RBRcoda Tu ensures high sensitivity in the low range (0-1000FTU), while the optical backscatter channel is designed for high-turbidity applications (up to 20000FTU). RBR calibrates the optical backscatter channel to ensure the highest accuracy around and above 1000FTU, thus achieving alignment between these two channels through their intended measurement conditions.

All optical components of the RBRcoda Tu are robust and durable, selected to minimise aging due to UV/sunlight exposure, and thus show no change in properties over extended deployments. Its sapphire windows facilitate automated cleaning by a wiper to keep them free of biofouling during long-term moored deployments.

**i** When used as a standalone sensor, the RBRcoda Tu has the additional capability to sample in aggregate mode. See [Ruskin User Guide: Sensors](#) for details.



**RBRcoda Tu**

### Turbidity

Parameter	Value
Channel wavelength	880nm
Centroid angle	90°
Linearity, R <sup>2</sup>	0.99
Initial accuracy	5%
Calibrated range	0 - 1000FTU
Measurement range*	0 - 1500FTU
Detection limit	0.005FTU

\* Response becomes non-linear above 1000FTU.

### Turbidity (optical backscatter)

Parameter	Value
Channel wavelength	880nm
Centroid angle	135°
Linearity, R <sup>2</sup>	0.99
Initial accuracy	5%
Calibrated range	1000 - 4000FTU
Measurement range*	0 - 20000FTU
Detection limit	2.0FTU

\* Response becomes non-linear below 500FTU and above 15000FTU.

### Physical

Parameter	Value
Housing	Titanium
Diameter	25mm
Length	~65mm (~100mm with connector)
Weight	110g in air, 70g in water
Depth rating	Up to 6000m
Sampling rate	Up to 32Hz

### Power

Parameter	Value
Supply voltage	4.5V to 30V (12V nominal)
Power	2.3mJ/sample (4Hz or slower) 42mW (8Hz or faster)
Sleep current	10µA at 12V

## 2.7 RBRcoda<sup>3</sup> DO ( OxyGuard)

The RBRcoda<sup>3</sup> DO uses the OxyGuard galvanic dissolved oxygen sensor. The sensor consumes oxygen from the environment and thus produces most accurate measurements when in a stirred environment. During deployments, always orient the sensor downwards to reduce debris collecting at the aperture and minimise direct sunlight. Store the sensor in the dedicated storage cap, included with the instrument.



### RBRcoda<sup>3</sup> DO (OxyGuard)

#### Dissolved Oxygen

Parameter	Value
Range	0 to 600%
Initial accuracy	±2% oxygen saturation
Resolution	1% of saturation
Response time	~10s, 90% step change at 20°C

#### Physical

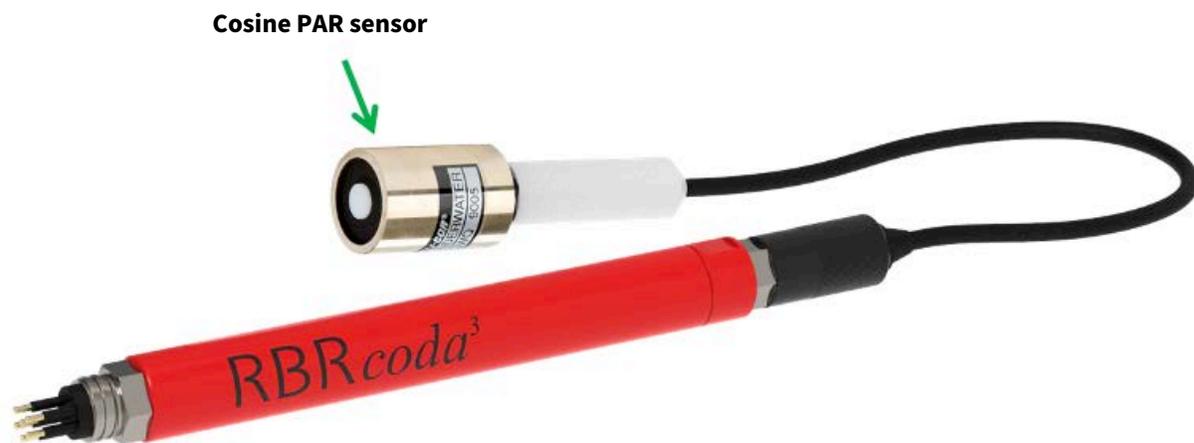
Parameter	Value
Housing	Plastic
Diameter	25mm
Length	~125mm (~160mm with connector)
Weight	190g in air, 70g in water
Depth rating	Up to 1700m
Sampling rate	2Hz

#### Power

Parameter	Value
Supply voltage	6V to 18V (12V nominal)
Power	10mA/120mW at 12V

## 2.8 RBRcoda<sup>3</sup> PAR (LI-COR)

The RBRcoda<sup>3</sup> PAR (LI-COR) instruments use cabled cosine (one hemisphere, LI-192) or spherical (omnidirectional, LI-193) PAR sensors.



**RBRcoda<sup>3</sup> PAR (LI-COR) variants**

**PAR**

<b>Parameter</b>	<b>Value</b>
Wavelength range	400 to 700nm
Calibrated range	0 to 10000 $\mu$ mol/m <sup>2</sup> /s
Initial accuracy	$\pm$ 2%

**Physical**

<b>Parameter</b>	<b>Value</b>
Housing	Plastic
Diameter	~25mm
Length	~265mm (~300mm with connector) cable 0.6m
Weight	460g in air, 240g in water (cosine) 400g in air, 100g in water (spherical)
Depth rating	Up to 560m (cosine) Up to 350m (spherical)
Sampling rate	2Hz

**Power**

<b>Parameter</b>	<b>Value</b>
Supply voltage	6V to 18V (12V nominal)
Power	10mA/120mW at 12V

## 3 Derived parameters

The RBR realtime smart sensors stream the data already calibrated, with all the parameters derived.

See Ruskin User Guide: RBR Sensors for instructions on configuring your instrument.

### 3.1 Sea pressure

Sea pressure is the difference between the pressure measured underwater by your RBR instrument and atmospheric pressure. The units of measurement are **dbar** (decibars).

$$\text{Sea pressure} = \text{absolute pressure} - \text{atmospheric pressure}$$

where pressure (in dbar) is the value measured directly by your RBR instrument.

Enter atmospheric pressure (in dbar) manually in the table under the **Parameter** tab in Ruskin. See Ruskin User Guide: RBR Sensors. If not entered, a default value of 10.1325dbar will be used.

### 3.2 Depth

Depth is a function of sea pressure and seawater density. The units of measurement are **m** (metres).

$$\text{Depth} = \frac{\text{sea pressure}}{\text{density} \cdot g}$$

where seawater density is in  $\text{g/cm}^3$  and sea pressure is in dbar, and  $g$  is the acceleration of gravity and equals  $9.8\text{m/s}^2$ .

Sea pressure is also a derived parameter:

$$\text{Sea pressure} = \text{absolute pressure} - \text{atmospheric pressure}$$

Enter atmospheric pressure (in dbar) and seawater density (in  $\text{g/cm}^3$ ) manually in the table under the **Parameter** tab in Ruskin. See Ruskin User Guide: RBR Sensors. If not entered, default values of 10.1325dbar and  $1.0281\text{g/cm}^3$  will be used.

### 3.3 Oxygen concentration

The RBR*coda*<sup>3</sup> DO supports a third-party DO sensor from OxyGuard, which measures dissolved oxygen saturation.

When a sensor measures oxygen saturation, we can derive oxygen concentration using the Weiss equation. See [The solubility of nitrogen, oxygen and argon in water and seawater](#) by R.F. Weiss for details.

The units of measurement may be **μMol/L**, **mg/L**, or **mL/L**.

The Weiss equation requires values for absolute temperature (in °K) and salinity, which are derived from measured temperature and conductivity. As your instrument does not measure conductivity, a default value of 35PSU will be used. Alternatively, enter conductivity manually in the table under the **Parameter** tab in Ruskin. See Ruskin User Guide: RBR Sensors.

### 3.4 Oxygen saturation

The RBR*coda*<sup>3</sup> T.ODO measures dissolved oxygen concentration.

When a sensor measures oxygen concentration, we derive oxygen saturation using the Garcia and Gordon equation. See [Oxygen solubility in seawater: better fitting equations](#) by F. H. Garcia and I. I. Gordon for details.

The units of measurement are %.

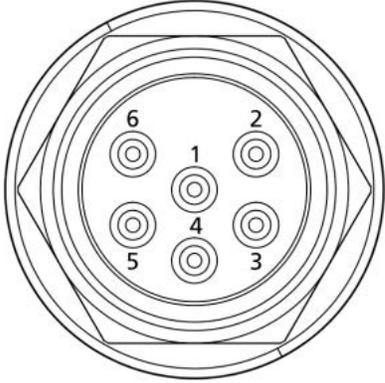
The Garcia and Gordon equation requires values for absolute temperature (in °K) and salinity, which are derived from measured temperature and conductivity. As your instrument does not measure conductivity, a default value of 35PSU will be used. Alternatively, enter conductivity manually in the table under the **Parameter** tab in Ruskin. See Ruskin User Guide: RBR Sensors.

## 4 Connector pinouts

### 4.1 MCBH connectors

All RBR smart sensors have an **MCBH-6-MP** connector to connect to your computer or to use for integrations with the RBR standard instruments. The data will stream via a patch cable (ordered separately).

Pin No.	RS-232
1	Ground
2	Power
3	From the sensor (Tx)
4	Into the sensor (Rx)
5	N/C
6	N/C



**RBRcoda Tu with an MCBH connector**

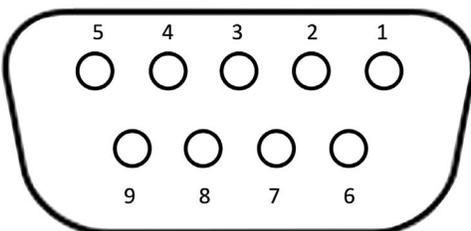
## 4.2 DB9 connectors

RBR smart sensors use RS-232 patch cables for connecting to your computer and power supplies. Depending on the ordered configuration, your patch cable may have an embedded converter and either a USB connector or a **DB9-F** connector.

Refer to RBR Cable Guide for available options.

### Patch cable DB9-F connector pinout

Pin No.	RS-232
1	N/C
2	From the instrument (Tx)
3	Into the instrument (Rx)
4	N/C
5	Drain/Ground
6	Ground
7	Auxiliary
8-9	N/C



**RBRcoda<sup>3</sup> D with an RS-232 cable, DB9-F connector**

## 5 Maintenance

### 5.1 Deployment

The RBR smart realtime sensors are robust and reliable, but there are several things to keep in mind when deploying them. Proper deployment will ensure faultless operation and preserve your data.

#### Precautions

1. Do not exceed the maximum depth rating.

**⚠** All RBR sensors are individually rated to a maximum depth in meters, as indicated on the label.



2. Do not apply physical stress to the housing.

**⚠** Stress due to improper mounting may cause the RBR sensors to leak, resulting in the loss of valuable data or permanent damage to the electronics. Any type of clamp or bracket which concentrates the stress on the housing is not recommended for use in mooring, mounting, and/or other deployment. Contact [RBR](#) for proper mooring and mounting clamps suited to your specific application.

3. Do not attempt to open the sensor.

**⚠** All RBR sensors are sealed and cannot be opened by the user. Any attempt to do so will damage the sensor and void all warranty.

## 5.2 Cables and connectors

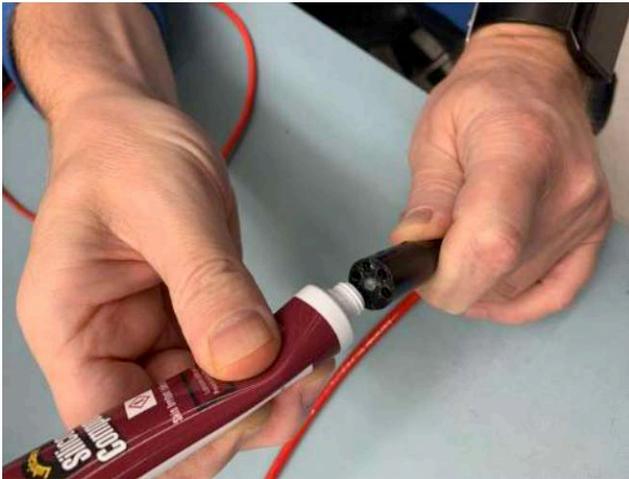
### Cable bend radius

The smallest bend radius for RBR supplied cables is 15cm.

### Lubricating the connectors

Lubrication improves watertight sealing, prevents corrosion, and reduces the force required to de-mate the connector. Use the silicone compound provided with your instrument.

- Apply the silicone compound to all female connectors before every mating
- Ensure each connector hole is filled with approximately 30% lubricant



**Lubricating a connector**

### Reducing mechanical stress

- Do not pull on the cable
- Hold onto the connector to pull out the cable
- Disconnect by pulling straight out, not at an angle
- Avoid sharp bends at the point where the cable enters the connector
- Avoid angular loads on the connector

## 5.3 RBR ODO sensor care and maintenance

The RBR optical dissolved oxygen sensors have an oxygen-sensitive substrate that requires special care. Any damage will permanently affect performance.

- ✘ Avoid direct sunlight.  
Never touch the sensitive element while cleaning or handling.  
Use the storage cap when the sensor is not in use.

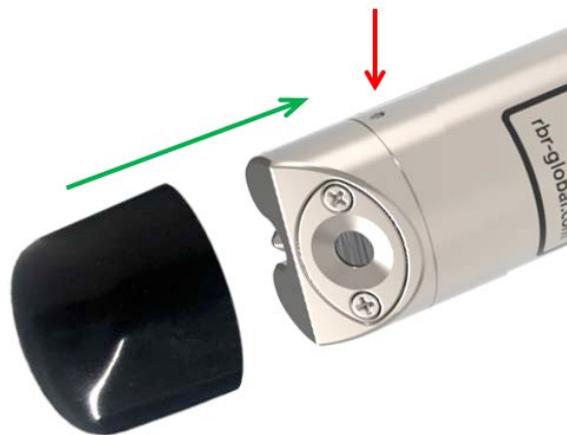
### Storage

Store the RBR optical dissolved oxygen sensor in the dedicated storage cap to protect it from damage.

Storage caps are provided with the instrument. Contact [RBR](#) if a replacement is needed.

- **Short-term storage (three weeks or less)**

1. Fill the storage cap with clean water until about 50% full.
2. Place the cap on the sensor and gently push it past the locking pin.
3. Refill the water periodically during storage. The cap is semi-watertight and will leak overtime.



**Push the storage cap past the locking pin**

- **Long-term storage (more than three weeks)**

- ⚠ For longer storage periods, store your sensor dry. Rehydrate for **five** days before deployment.

1. Place an empty cap on the sensor and gently push it past the locking pin.
2. Before deployment, fill the storage cap with clean water like for short-term storage, place it on the sensor, and rehydrate for **five** days.

- ✘ It takes up to five days for a dry ODO sensor to equilibrate after being placed in water. Insufficient hydrating time before deployment may lead to unreliable data.



**RBRcoda<sup>3</sup> T.ODO ready for storage**

### Storage cap variants

RBR ODO sensors intended for vehicle integration are shipped with a specialised storage cap, designed for a sensor mounted inside the glider. This storage cap has an opening for refilling the water with a syringe. See the quick start guide provided with your sensor for more information.



**RBRcoda<sup>3</sup> T.ODO for vehicle integration**

### First deployment

RBR ships the RBRcoda<sup>3</sup> T.ODO instruments with a hydrated storage cap on, so that the instrument is ready for its first deployment.

However, long transportation times and low cabin pressure may result in the loss of water. Verify that the storage cap is still wet. If not, rehydrate the sensor for **five days** before deployment.

### Calibration

Check your sensor calibration before each deployment in saturated fresh water. If the readings are not within 1% of 100% saturation, recalibrate the instrument using a one-point calibration. Typically, | fast instruments may need recalibration more often than standard or | slow. See [Ruskin User Guide: Sensors](#) for user calibration instructions.

## 5.4 DO sensor (OxyGuard) care and maintenance

### Storage

Store the OxyGuard dissolved oxygen sensor in the dedicated storage cap to minimise fluid loss. Storage caps are provided with the instrument. Contact RBR if a replacement is needed.



### O-ring

The red O-ring of the OxyGuard sensor serves two purposes:

- To retain the electrolyte during storage
- To balance pressure during deployments

There are two positions for O-ring on the OxyGuard sensor, "Transport" and "Measurement".



During transportation or storage, move the red O-ring of the Oxyguard sensor to the "Transport" position, closing off the port on the side of the cell.

Before deployment, move the O-ring to the "Measurement" position to maintain the pressure balance.

After deployment, return the O-ring to the "Transport" position.



### Support kit

RBR offers an OxyGuard sensor support kit that includes:

- Membrane tool
- Electrolyte solution (250ml)
- Fast response membranes
- Replacement O-rings
- Oxyguard Support Kit and Refurbishment Guide

Check the state of your DO sensor before deployment. Look for any damage to the membrane, cloudiness of the electrode, and buildup on the anode. If you find any damage, refurbish and re-calibrate the sensor.

Refer to Oxyguard Support Kit and Refurbishment Guide, included with the support kit, for instructions on refurbishing your sensor. See [Ruskin User Guide: RBR Sensors](#) for instructions on calibration.

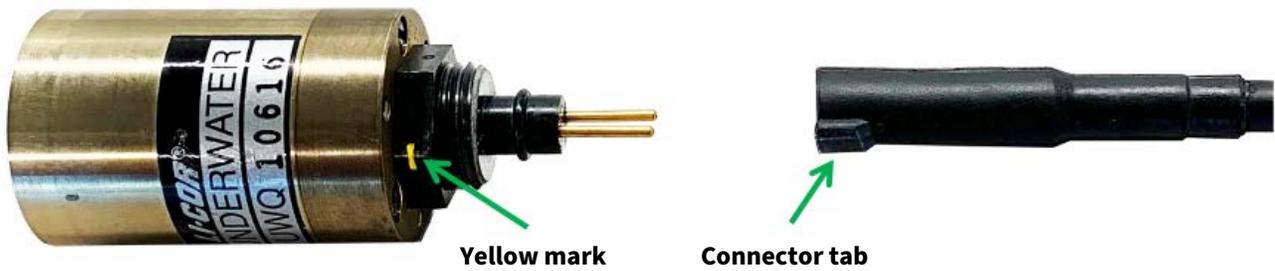
## 5.5 PAR sensor (LI-COR) connector alignment

Proper connection between the PAR sensors (LI-COR) and their cable is crucial for deployment success.

Both LI-192 and LI-193 have a two-pin connector with a small yellow mark on the side.



Always align this yellow mark with the tab on the side of the cable connector when connecting the sensor to its cable.



### Orientation:

After connecting the cable to the PAR sensor, confirm that the yellow mark and the connector tab are aligned, and then put the white locking sleeve in place. The sensor is ready for deployment.

⚠️ Ensure proper orientation of the yellow mark and the tab before each deployment. Inverted connection of your PAR sensor will result in incorrect or lost data.

## 5.6 Cleaning

Clean the instrument after each extended deployment to remove deposits that may have accumulated.

✘ Do not use an ultrasonic bath to clean your instruments! Ultrasonic vibrations can break the wire bonding inside the transducers.

Type	Procedure	Notes
General/biofouling	To clean the exterior, soak in a mild detergent, then scrub the instrument with a soft brush.	Avoid scratching the plastic (scratches make future cleaning more difficult).
Calcification, encrustation	Soak in vinegar for six hours, then scrub the surface using a soft brush.	Soaking in vinegar for more than 24 hours may damage the O-ring and increase the chances of a leak.

### Cleaning the pressure sensor

✘ Avoid touching the diaphragm when cleaning the sensor! Any deformation will permanently affect performance.

1. Unscrew the sensor guard using a coin or a large flathead screwdriver. Do not apply excessive force, especially when using the screwdriver.
2. Rinse the area under running water. If this fails to remove the deposits, try soaking in vinegar.
3. If unsuccessful, contact RBR.

### Cleaning PAR, rad, and ODO sensors

When dirty, carefully wipe the sensors with a soft cloth. To remove encrustation, soak in water until soft. It may take hours or days, depending on the severity.

✘ Do not use abrasive cloths as scratched faces can affect calibration.  
Do not use solvents or cleaners as these could affect optical properties of the window.

## 5.7 Calibration

Factory calibration coefficients are calculated for each sensor, and the coefficients are stored on the instrument.

RBR calibration certificates contain calibration equations, coefficients, and residuals for each sensor.

Calibration certificates are available for download:

- If using Ruskin, connect your instrument and go to the “Information” tab, then click “Download” at the bottom
- For OEM instruments, go to <https://oem-lookup.RBR-global.com>, middle tab, and search by the serial number and authorisation key

RBR recommends calibrating your instrument before any critical deployment, periodically once a year, or if you suspect the readings to be out of specifications.

Discuss your calibration requirements with RBR. In some cases, the instrument will need to be returned to RBR to have it checked and recalibrated.

Please contact [RBR](#) for our current calibration fees.

## 5.8 Repairs

RBR supports all our products. Contact us immediately at [support@rbr-global.com](mailto:support@rbr-global.com) or via the [RBR website](#) if there are any issues with your instrument. Please have the model and the serial number of the unit ready. Our support team will work to resolve the issue remotely. In some cases, you may have to return your instrument to RBR for further servicing.

 There are no user-repairable parts of the instrument. Any attempt to repair without prior authorisation from RBR will void the warranty. Refer to the [RBR warranty statement](#).

To return a product to RBR for an upgrade, repair, or calibration, please contact our [support team](#) to obtain a return merchandise authorisation code (RMA) and review the detailed shipping information on the [RBR website](#).

## 6 Revision history

Revision No.	Release date	Notes
A-H	2021-2023	Various
J	30-June-2024	Added phycocyanin and phycoerythrin to the RBR <i>tridente</i> options in the Introduction. Updated the RBR <i>coda</i> <sup>3</sup> T.ODO specifications for accuracy and resolution, and to include the   slow variant in the image. Updated the RBR <i>quadrante</i> specifications for wavelength options, and RBR <i>tridente</i> specifications for new parameter options, depth rating, and OEM variant. Added a warning against using the ultrasonic bath to the Cleaning section.
K	15-August-2024	Added the   slow variant to the image in the RBR <i>coda</i> <sup>3</sup> T.ODO section. Updated the RBR <i>tridente</i> section for the OEM variant, wavelengths, weight specifications.
L	15-November-2024	Added a note on aggregate mode to the introduction. Updated specifications for the RBR <i>coda</i> <sup>3</sup> PAR, RBR <i>coda</i> <sup>3</sup> rad. Removed the RBR <i>quadrante</i> and RBR <i>tridente</i> sections (now available as a dedicated instrument guide). Added the RBR <i>coda</i> Tu section. Updated the Calibration section for downloading instructions.

